Reasoning about Strategies under Partial Observability and Fairness Constraints

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Running Example: A simple card game [1]

Three cards: A, K, Q (A wins over K, K over Q, Q over A);

A player, a dealer.



[1] W. Jamroga, W. van der Hoek. Agents that Know How to Play. (2004)

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the player can change his card with the one on table.



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Variant: the player can play infinitely.

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Running Example: A simple card game



Model checking problem: does the player have a strategy to win?

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 \Rightarrow it depends on the semantics!

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Under *ATL*, we consider all strategies. The player has a strategy to win, even if he cannot play it: e.g., in $\langle A, K \rangle$, keep the card; in $\langle A, Q \rangle$, exchange it.

Model checking problem: does the player have a strategy to win?

ATL: yes.

Under ATL_{ir} , we consider only **memoryless uniform** strategies. There is no uniform strategy to win, because the player cannot distinguish, e.g., $\langle A, K \rangle$ and $\langle A, Q \rangle$.

Model checking problem: does the player have a strategy to win?

ATL: yes.

ATL_{ir}: no.

If we consider ATL_{ir} with a **fair dealer** and an **infinite play**, the player can eventually win: just use one uniform strategy, the right pair will finally come.

Model checking problem: does the player have a strategy to win?

ATL: yes.

ATL_{ir}: no.

 ATL_{ir} + fair dealer and infinite play: yes.

 \Rightarrow *ATLK*_{*irF*}: branching time, knowledge, **memoryless uniform** strategies and unconditional **fairness constraints**.

Outline

Strategies, Temporal Logics and Fairness

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Discussions

Implementation

Conclusion

ATL, reasoning about strategies of the agents. [2]

Syntax: Strategic modalities: $\langle \Gamma \rangle \mathbf{X} \phi$, $[\Gamma] \mathbf{G} \phi$, $\langle \Gamma \rangle [\phi_1 \mathbf{U} \phi_2]$, etc.

Semantics: A state *s* satisfies $\langle \Gamma \rangle \pi$ iff there exists a set of **strategies** for agents in Γ such that **all enforced paths satisfy** π .

[2] Alur et al. Alternating-time temporal logic. (2002)

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Model checking:

$$eval_{ATL}([\Gamma]\mathbf{G} \phi) = \nu Z.eval_{ATL}(\phi) \cap Pre_{[\Gamma]}(Z)$$

where $Pre_{[\Gamma]}(Z)$ is the set of states from which Γ cannot avoid to reach Z in one step.

[2] Alur et al. Alternating-time temporal logic. (2002)

ATL_{ir}, memoryless uniform strategies [3]

Only memoryless uniform strategies:

$$f_a:S
ightarrow Act_a$$
 such that $s\sim_a s'\implies f_a(s)=f_a(s')$

Semantics: A state *s* satisfies $\langle \Gamma \rangle \pi$ iff there exists a set of **memoryless uniform** strategies for agents in Γ such that all paths enforced **from all** $s' \sim_{\Gamma} s$ satisfy π .

[3] Schobbens. Alternating-time logic with imperfect recall. (2004).

FairCTL: time and fairness constraints [4]

Add a set of **fairness constraints** $FC \subseteq 2^S$ to the model; \Rightarrow unconditional state-based fairness.

Only fair paths are considered:

- $s \models \mathbf{E} \pi$ iff there exists a **fair** path from *s* satisfying π ;
- $s \models \mathbf{A} \pi$ iff all **fair** paths from *s* satisfy π .

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Model checking:

$$eval_{FCTL}(\mathsf{EG} \ \phi) = \nu Z.\Phi \cap \bigcap_{fc \in FC} Pre(\mu Y.(Z \cap fc) \cup (\Phi \cap Pre(Y)))$$

where Pre(Z) is the set of states having a successor in Z and $\Phi = eval_{FCTL}(\phi)$.

[4] Clarke, Grumberg, Peled. Model checking. (2000).

Adding fairness constraints to the card game



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$ATLK_{irF} = FairCTL$, knowledge and ATL_{ir} with fairness

Syntax: CTL (**EX**, **AG**, etc.), knowledge (K_{ag} , C_{g} , etc.) and strategies ($\langle \Gamma \rangle F$, [Γ]U, etc.)

Semantics: A state *s* satisfies $\langle \Gamma \rangle \pi$ iff there exists a **memoryless uniform** strategy for Γ such that all **fair** paths enforced **from all** $s' \sim_{\Gamma} s$ satisfy π . To model check $ATLK_{irF}$, we defined $ATLK_{IrF}$ and its model checking

 $ATLK_{IrF} = FairCTL + knowledge + ATL with fairness$

ATLK_{IrF} semantics: A state s satisfies $\langle \Gamma \rangle \pi$ iff there exists a memoryless strategy (not necessarily uniform) for Γ such that all fair paths enforced (from s only) satisfy π .

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ATLK_{IrF} semantics: A state s satisfies $\langle \Gamma \rangle \pi$ iff there exists a memoryless strategy (not necessarily uniform) for Γ such that all fair paths enforced (from s only) satisfy π .

ATLK_{IrF} model checking:

 $eval_{IrF}([\Gamma]\mathbf{G} \phi) = \nu Z.\Phi \cap \bigcap_{fc \in FC} Pre_{[\Gamma]}(\mu Y.(Z \cap fc) \cup (\Phi \cap Pre_{[\Gamma]}(Y)))$

where $\Phi = eval_{IrF}(\phi)$.

A state s satisfies $\langle \Gamma \rangle \pi$ iff there exists a **memoryless uniform** strategy for Γ which allows Γ to enforce π in all states indistinguishable from s, considering only fair paths. A state s satisfies $\langle \Gamma \rangle \pi$ iff there exists a **memoryless uniform** strategy for Γ which allows Γ to enforce π in all states indistinguishable from s, considering only fair paths.

To get all the states satisfying $\langle \Gamma \rangle \pi$:

- 1. List all the memoryless uniform strategies;
- Use ATLK_{IrF} model checking to get states satisfying the property in this strategy;
- 3. Then restrict to set of undistinguishable states.

ATLK_{irF} model checking: Split algorithm

Split the state/action pairs into memoryless uniform strategies.

- 1. Get all conflicting equivalence classes;
- 2. If there are none, the set is itself a memoryless uniform strategy.
- 3. Otherwise, choose a conflicting equivalence class;
- 4. Split it;
- 5. and recursively call *Split* on the rest.















Apply $ATLK_{IrF}$ model checking \Rightarrow all states satisfy the property; \Rightarrow the strategy is winning for all.

$$s \not\models_{\mathit{IrF}} \langle \Gamma \rangle \pi \implies s \not\models_{\mathit{irF}} \langle \Gamma \rangle \pi$$

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 \Rightarrow Can only consider the states satisfying $\langle \Gamma \rangle \psi$ under $ATLK_{IrF}$;

$$s \not\models_{IrF} \langle \Gamma \rangle \pi \implies s \not\models_{irF} \langle \Gamma \rangle \pi$$

 \Rightarrow Can only consider the states satisfying $\langle \Gamma \rangle \psi$ under $ATLK_{IrF}$;

 \Rightarrow Can only consider actions that allow Γ to win under $ATLK_{IrF}$;

$$s \not\models_{IrF} \langle \Gamma \rangle \pi \implies s \not\models_{irF} \langle \Gamma \rangle \pi$$

 \Rightarrow Can only consider the states satisfying $\langle \Gamma \rangle \psi$ under $ATLK_{IrF}$;

 \Rightarrow Can only consider actions that allow Γ to win under $ATLK_{IrF}$;

 \Rightarrow Can alternate between filtering states and actions and splitting equivalence classes into non-conflicting subsets.

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Complexity

$ATLK_{IrF}$ is in **P**: the proposed algorithm is polynomial.

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 $ATLK_{irF}$ subsumes ATL_{ir} (in the case of two agents) $\Rightarrow ATLK_{irF}$ is Δ_2^P -hard;

Split algorithm is in **NP** $\Rightarrow ATLK_{irF}$ is Δ_2^P -complete. If Γ have a strategy **producing no fair path**, Γ can win any objective;

in particular, **unsatisfiable formulas** like $\langle \Gamma \rangle F$ false.

If Γ have a strategy **producing no fair path**, Γ can win any objective; in particular, **unsatisfiable formulas** like $\langle \Gamma \rangle \mathbf{F}$ false.

Solutions

- consider only groups of agents that cannot prevent fairness;
- change the semantics to only consider strategies producing at least one fair path;

• ...

Knowledge relations

A state s satisfies $\langle \Gamma \rangle \pi$ under $ATLK_{irF}$ iff there exists a memoryless **uniform** strategy for Γ which allows Γ to enforce π in all **states indistinguishable from** s, considering only fair paths.

Distributed knowledge used for both relations

- \Rightarrow Γ is considered as a unique agent
- \Rightarrow the simplest form.

Knowledge relations

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- \Rightarrow the simplest form.

We could consider other knowledge relations:

- one knowledge relation per agent of Γ (used by ATL_{ir} for uniformity);
- group knowledge;
- common knowledge.

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Prototype implemented with PyNuSMV, a Python framework based on NuSMV [5].

Several tested implementations.

[5] S. Busard, C. Pecheur. PyNuSMV: NuSMV as a Python Library. (2013)

Basic algorithm:

- 1. splitting the entire system into uniform strategies;
- 2. checking each strategy.

 \Rightarrow explodes quickly, huge number of strategies (huge number of combinations of choices for actions).

Improved algorithm:

Alternate between filtering out losing states and actions and splitting one conflicting equivalence class.

 \Rightarrow slower explosion, especially when only a few states satisfy the property.

Implementation and tests

Mixing both:

- 1. filtering out losing states and actions;
- 2. splitting the rest into uniform strategies;
- 3. checking each strategy.

 \Rightarrow best solution:

most of the filtering work is performed by the first filtering.

More improvements (current work)

1. Partial strategies: check only strategies "that matter".

- 2. Implementation optimizations:
 - early termination: stop when a strategy is found for all states;
 - caching: remember states satisfying sub-formulas through different strategies;
 - ▶ ...

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ATLK_{irF}: branching time, knowledge and strategies under partial observability and (unconditional state-based) fairness constraints.

(Symbolic) model checking algorithm based on $ATLK_{IrF}$ model checking and splitting the graph into memoryless uniform strategies.

Conclusion

ATLK_{irF}: branching time, knowledge and strategies under partial observability and (unconditional state-based) fairness constraints.

(Symbolic) model checking algorithm based on $ATLK_{IrF}$ model checking and splitting the graph into memoryless uniform strategies.

- \Rightarrow Still needs some improvements.
- \Rightarrow Work on counter-examples (controller synthesis,...)

Thank you.

Questions?